

## SEMILINEAR PROBLEMS PERTURBED THROUGH THE BOUNDARY CONDITION\*

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**Abstract.** We analyze the semilinear diffusion equation  $\Delta u = a(x)u^p$  in a smooth bounded domain  $\Omega$  subjected to the boundary condition  $\partial u/\partial \nu = \lambda u$ , where  $\nu$  is the outward unit normal to  $\partial\Omega$ ,  $\lambda$  is a real parameter. The coefficient  $a(x)$  is a nonnegative weight function, which could even vanish in a whole smooth subdomain  $\Omega_0$  of  $\Omega$ . We consider both cases  $p > 1$  and  $0 < p < 1$ , and give a detailed description of the existence, uniqueness or multiplicity and asymptotic behavior of nonnegative solutions. As an additional special feature, the adherence of the portions  $\Omega \cap \partial\Omega_0$ ,  $\partial\Omega \cap \partial\Omega_0$  of the boundary of  $\Omega_0$  are allowed to meet each other in a smooth manifold.

**Key words.** Bifurcation, Steklov problem, boundary blow-up, perturbation of domains.

**AMS subject classifications.** 35J25, 35B40.

**1. Introduction.** In this note we are giving a summary of the issues of existence and uniqueness – alternatively multiplicity – of positive solutions to the semilinear problem:

$$\begin{cases} \Delta u = a(x)u^p & x \in \Omega \\ \frac{\partial u}{\partial \nu} = \lambda u & x \in \partial\Omega, \end{cases} \quad (1.1)$$

where  $\Omega \subset \mathbb{R}^N$  is a  $C^{2,\alpha}$  bounded domain,  $a(x) \in C^\alpha(\overline{\Omega})$ ,  $a(x) \geq 0$ .

The main features of problem (1.1) are: a) the presence of the bifurcation parameter  $\lambda$  in the boundary condition, b) the possibility that  $a \geq 0$  can vanish in a whole subdomain  $\Omega_0$  of  $\Omega$  and c) the two regimes of the problem: “regular” and “degenerate”, corresponding to the ranges  $p > 1$  and  $0 < p < 1$  of the exponent  $p$  respectively. In particular, we are paying special attention to the study of the asymptotic profiles of the solutions when the parameter  $\lambda$  tends to critical values  $\lambda_c$  where bifurcation phenomena occur. In the degenerate case, the study of the regions where the solutions  $u$  vanish identically (“dead cores”) will be an additional issue to deal with.

Problem (1.1) constitutes another example of the group of models where a “dissipative” (“absorption”) mechanism is in competition with another one of “production” (“radiation”). The logistic problem under either of the three classical boundary conditions is the paradigmatic example of this setting (see [8], [2], [6], [1] for the discussion of phenomena which are related to the ones covered here).

In the rest of the note we will assume that the coefficient  $a(x)$  verifies the following hypothesis:

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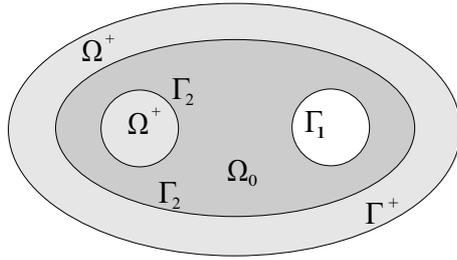


FIG. 1.1. A possible configuration for an  $\Omega_0$  satisfying  $H)_s$ .

H)  $a \in C^\alpha(\overline{\Omega})$  is nonnegative and nontrivial. Moreover, it is either strictly positive in  $\Omega$  or  $a \equiv 0$  in a subdomain  $\Omega_0 \subset \Omega$  of class  $C^{2,\alpha}$ .

For immediate reference we are fixing the following notations:  $\Gamma_2 = \Omega \cap \partial\Omega_0$ ,  $\Gamma_1 = \partial\Omega_0 \setminus \Gamma_2$ . In addition,  $\Omega^+ = \{x \in \Omega : a(x) > 0\}$ ,  $\Gamma^+ = \partial\Omega^+ \cap \partial\Omega$ . Notice that since  $a(x)$  is nontrivial then both  $\Gamma_2$  and  $\Omega^+$  must always be non void meanwhile  $\Omega \cap \partial\Omega^+ = \Gamma_2$ .

In our previous works [3], [4], an important part of the results was obtained under the simplifying assumption,

$$H)_s \quad \overline{\Gamma}_2 = \Gamma_2,$$

the bar standing for “adherence”. This means that  $\Gamma_2$  is a closed  $N - 1$  dimensional manifold and, more importantly, that  $\Gamma_1$  is separated away from  $\Gamma_2$  ( $\text{dist}(\Gamma_1, \Gamma_2) > 0$ ). In particular,  $\Omega^+$  also defines a  $C^{2,\alpha}$  subdomain of  $\Omega$ , while  $\Omega_0, \Omega^+, \Gamma_1, \Gamma_2, \Gamma^+$  consist only of a finite number of connected pieces (Figure 1.1). We are reviewing the above mentioned results in Sections 3 and 4.

In the present work some of the main statements in [3] are significantly extended to cover more natural configurations for  $\Gamma_1, \Gamma_2$  in  $\partial\Omega_0$  than in  $H)_s$ . In particular, allowing  $\overline{\Gamma}_2 \cap \Gamma_1 \neq \emptyset$  (see details in Sections 3, 4 and Figure 3.2).

REMARK 1. The connectedness condition in  $\Omega_0$  can be relaxed without significative changes in the results.

**2. Eigenvalue problems.** In the analysis of (1.1) several eigenvalue problems which are non-standard appear. In fact, some of them involve the eigenvalue in the boundary condition while other ones exhibit a non usual regime for the coefficients.

A first eigenvalue problem is

$$\begin{cases} \Delta\phi = \lambda\phi & x \in \Omega_0 \\ \frac{\partial\phi}{\partial\nu} = \mu\phi & x \in \partial\Omega, \end{cases} \quad (2.1)$$

$\mu > 0$  regarded as a parameter. The existence of a principal eigenvalue  $\lambda_1(\mu)$  to (2.1) and its qualitative behavior with respect  $\mu$  was first studied in [7] and extended in several aspects in [3]. The corresponding principal eigenfunctions  $\phi$  are a source of sub and supersolutions for problem (1.1) in the regime  $p > 1$ .

The description of the set of positive solutions for problem (1.1) when  $\Omega_0 \neq \emptyset$  requires the introduction of several critical values for  $\lambda$ , characterized by means of some eigenvalue problems. Specifically, we define  $\lambda = \sigma_1$  as the principal eigenvalue

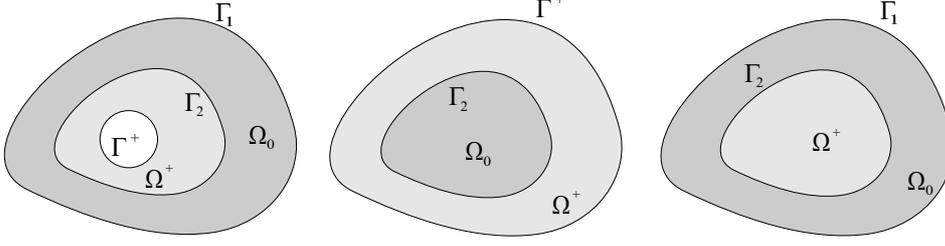


FIG. 2.1. Several configurations for  $\Omega_0$  and  $\Omega^+$ :  $\Gamma_1, \Gamma^+ \neq \emptyset$ ,  $\Gamma_1 = \emptyset, \Gamma^+ \neq \emptyset$  and  $\Gamma_1 \neq \emptyset, \Gamma^+ = \emptyset$ .

of the mixed Steklov-type eigenvalue problem:

$$\begin{cases} \Delta\phi = 0 & x \in \Omega_0 \\ \phi = 0 & x \in \Gamma_2 \\ \frac{\partial\phi}{\partial\nu} = \lambda\phi & x \in \Gamma_1. \end{cases} \quad (2.2)$$

Since it could happen that  $\Gamma_1 = \emptyset$ , we set in that case  $\sigma_1 := \infty$  (Figure 2.1).

In the same way we introduce  $\lambda = \sigma_1^+$ , which is the corresponding principal eigenvalue of the problem:

$$\begin{cases} \Delta\phi = 0 & x \in \Omega^+ \\ \phi = 0 & x \in \Gamma_2 \\ \frac{\partial\phi}{\partial\nu} = \lambda\phi & x \in \Gamma^+. \end{cases} \quad (2.3)$$

We also set  $\sigma_1^+ := \infty$  whenever  $\Gamma^+ = \emptyset$ .

We refer to [3] for a detailed study of the properties of the eigenvalue problems (2.2), (2.3) and some other related problems. We remark that  $\sigma_1^+$  has to be suitably defined in case  $\Omega^+$  is not connected. In the first of the configurations in Figure 2.1, both  $\sigma_1$  and  $\sigma_1^+$  are finite. One of them becomes infinite in the rest of the configurations.

**3. The regime  $p > 1$ .** We are next describing the main features of problem (1.1) for the regular case where  $p > 1$ . In Theorems 3.1 to 3.3 it is assumed that  $a(x)$  satisfies H) together with the ‘‘separation’’ hypothesis  $H)_s$ . In the first statement the value  $\sigma_1 = \infty$  (see Section 2) is also used when referring to the case  $a(x) > 0$  in  $\Omega$ . Such results are collected in [3]. The section concludes with the study of the case where  $\Gamma_1$  and  $\bar{\Gamma}_2$  meet in a nontrivial way.

**THEOREM 3.1.** *Assume  $a(x)$  satisfies H),  $H)_s$  while  $p > 1$ . Then problem (1.1) admits positive solutions  $u \in C^{2,\alpha}(\bar{\Omega})$  if and only if:*

$$0 < \lambda < \sigma_1 \leq \infty,$$

*the solution  $u = u_\lambda(x)$  being unique in that case. Moreover, the mapping  $\lambda \mapsto u_\lambda$  is increasing and real analytic when considered with values in  $C^{2,\alpha}(\bar{\Omega})$ , and  $u_\lambda$  is globally attractive (among the positive solutions). Finally,  $u_\lambda \rightarrow 0$  as  $\lambda \rightarrow 0+$ , while  $|u_\lambda|_{\infty,\Omega} \rightarrow \infty$  when  $\lambda \rightarrow \sigma_1$ .*

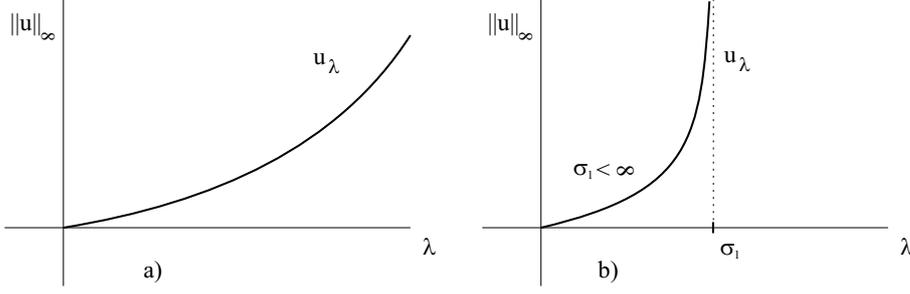


FIG. 3.1. a)  $a > 0$  in  $\Omega$  or  $\Omega_0 \neq \emptyset$  but  $\sigma_1 = +\infty$ , and b)  $\sigma_1 < +\infty$ .

REMARK 2. Theorem 3.1 allows the possibility that  $a(x)$  vanishes somewhere on  $\partial\Omega$  in the case where  $a(x)$  is positive in  $\Omega$  ( $\Omega_0 = \emptyset$ ), also permitting the existence of zeros for  $a(x)$  in  $\Gamma^+$  if both  $\Omega_0$  and  $\Gamma^+$  are nonempty ( $a(x) \equiv 0$  on  $\Gamma_1!$ ).

It has been established that if  $\Omega_0 \neq \emptyset$  and  $\sigma_1 < \infty$ , positive solutions disappear when  $\lambda$  crosses the value  $\sigma_1$ . The next results explain this interruption by analyzing the singularities developed by the solutions. Even if  $\sigma_1 = \infty$ , the solution  $u_\lambda$  approaches a finite profile in  $\Omega$  when  $\lambda$  tends to infinity.

THEOREM 3.2. Assume  $a(x) > 0$  for every  $x \in \Omega$ , or  $\Omega_0 \neq \emptyset$  but  $\sigma_1 = \infty$ . Then the solution  $u_\lambda$  of (1.1) satisfies  $u_\lambda \rightarrow u$  in  $C^{2,\alpha}(\Omega)$  as  $\lambda \rightarrow \infty$  where  $u(x)$  is the minimal solution to the singular boundary value problem:

$$\begin{cases} \Delta u = a(x)u^p & x \in \Omega \\ u = \infty & x \in \partial\Omega. \end{cases} \quad (3.1)$$

Moreover, we have the following estimate of the asymptotic growth rate:

$$\liminf_{\lambda \rightarrow \infty} \lambda^{-\frac{2}{p-1}} \sup u_\lambda \geq |a|_\infty^{-\frac{1}{p-1}}.$$

THEOREM 3.3. Under the condition  $\sigma_1 < \infty$  and hence  $\Gamma_1 = \partial\Omega_0 \cap \partial\Omega \neq \emptyset$ , the solution  $u_\lambda$  to (1.1) satisfies  $u_\lambda \rightarrow \infty$  uniformly in  $\bar{\Omega}_0$  as  $\lambda \rightarrow \sigma_1^-$ . In addition,  $u_\lambda \rightarrow u$  in  $C^{2,\alpha}(\Omega^+)$  where  $u(x)$  is the minimal solution to the singular boundary value problem:

$$\begin{cases} \Delta u = a(x)u^p & x \in \Omega^+ \\ u = \infty & x \in \Gamma_2 \\ \frac{\partial u}{\partial \nu} = \sigma_1 u & x \in \Gamma^+, \end{cases} \quad (3.2)$$

provided that  $\Gamma^+ = \partial\Omega^+ \cap \partial\Omega \neq \emptyset$ , or  $u(x)$  is the minimal solution to the problem:

$$\begin{cases} \Delta u = a(x)u^p & x \in \Omega^+ \\ u = \infty & x \in \partial\Omega^+, \end{cases} \quad (3.3)$$

in case  $\Gamma^+ = \emptyset$ .

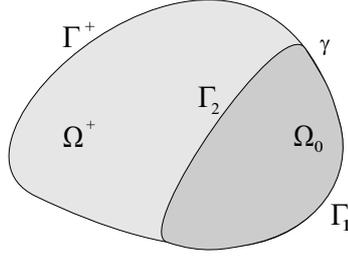


FIG. 3.2. Configuration for  $\Omega_0$  with  $\bar{\Gamma}_2$  and  $\Gamma_1$  contacting in a smooth manifold  $\gamma$ .

REMARK 3. Observe that we prove the existence of nontrivial solutions of (3.2). This is a novelty in view of the boundary condition on  $\Gamma^+$  not previously treated in the literature (see specially the corresponding problem in Theorem 3.4). On the other hand, suitable conditions on the weight  $a(x)$  can be given in order to obtain uniqueness of positive solutions to the singular problems (3.1), (3.2) and (3.3).

We are next dealing with the hypothesis H) under a less restrictive assumption than  $H)_s$  regarding the separation between  $\Gamma_1, \bar{\Gamma}_2$ . Namely, it will be assumed that  $\Omega_0 \subset \Omega$  is a  $C^3$  subdomain such that (recall that  $\Gamma_2 = \Omega \cap \partial\Omega_0$ ,  $\Gamma_1 = \partial\Omega \cap \partial\Omega_0$ ),

$H)_m$   $\Gamma_1, \bar{\Gamma}_2$  are nonempty  $N - 1$ -dimensional manifolds having as common boundary  $\gamma$ , a  $(N - 2)$ -dimensional closed submanifold of  $\partial\Omega$  (Figure 3.2).

The existence, under these conditions on  $\Omega_0$ , of a unique principal weak eigenvalue  $0 < \sigma_1 < \infty$  to (2.2) with a positive associated eigenfunction  $\phi_1 \in H^1(\Omega_0) \cap W^{2,s}(\Omega_0)$ ,  $1 < s < 4/3$ , can be ensured by variational methods (see [4]).

Our main statement concerning this new framework for problem (1.1) essentially asserts that Theorems 3.1 and 3.3 are still valid even when  $\Gamma_1$  and  $\bar{\Gamma}_2$  meet each other.

THEOREM 3.4. Suppose that  $a(x) \in C^\alpha(\bar{\Omega})$  satisfies H) together with condition  $H)_m$ . Then problem (1.1) admits a weak positive solution in  $H^1(\Omega)$  if and only if,

$$0 < \lambda < \sigma_1.$$

Such solution is unique and defines indeed a classical solution in  $C^{2,\alpha}(\bar{\Omega})$ . As a mapping of  $\lambda \in (0, \sigma_1)$ ,  $u_\lambda$  is increasing, smooth and bifurcates from zero at  $\lambda = 0$ . Moreover,

$$u_\lambda \rightarrow u,$$

as  $\lambda \rightarrow \sigma_1^-$  in  $C^{2,\alpha}(\Omega^+) \cap C^{1,\alpha}(\Omega^+ \cup T)$  for every compact  $T \subset \Gamma^+$  while,

$$u_\lambda \rightarrow \infty,$$

as  $\lambda \rightarrow \sigma_1^-$  uniformly on each compact set  $K \subset \Gamma_2$ . In particular:

$$\lim_{\text{dist}(x, K) \rightarrow 0} u(x) = \infty,$$

and thus  $u$  defines a classical solution to problem (3.2),

$$\begin{cases} \Delta u = a(x)u^p & x \in \Omega^+ \\ u = \infty & x \in \Gamma_2 \\ \frac{\partial u}{\partial \nu} = \sigma_1 u & x \in \Gamma^+. \end{cases}$$

REMARK 4. In contrast to the more regular case of the hypothesis  $H)_s$ , the approach to achieve existence in Theorem 3.4 is variational. In this regard, existence can be also obtained if  $\Omega_0$  is merely Lipschitz (cf. Theorem 2 in [3]). An additional regularity argument then shows that any weak  $H^1(\Omega)$  solution to (1.1) lies indeed in  $L^\infty(\Omega)$  and hence its smoothness improves up to be a classical solution (see further details in [5]). On the other hand, it is a more subtle question to decide which is the possible asymptotic profile of  $u_\lambda$  in the interphase  $\gamma$  as  $\lambda \rightarrow \sigma_1^-$ .

**4. Degenerate regime.** Let us now analyze problem (1.1) in the degenerate range  $0 < p < 1$ . The results we describe in what follows are contained in the work [4] with the exception of those involving the condition  $H)_m$ . We are denoting  $\alpha_1 = \min\{p, \alpha\}$ .

THEOREM 4.1. *Assume that the coefficient  $a(x) \in C^\alpha(\bar{\Omega})$  satisfies  $a(x) > 0$  for every  $x \in \Omega$ . Then:*

- i) [Existence] *Problem (1.1) admits at least a nonnegative solution  $u \in C^{2,\alpha_1}(\bar{\Omega})$ ,  $u \neq 0$ , for every  $\lambda > 0$  and no nonnegative solutions exist if  $\lambda \leq 0$ .*
- ii) [Bifurcation from infinity] *For certain  $\lambda_0 > 0$  small enough and  $0 < \lambda < \lambda_0$  there exists a unique positive solution  $u_\lambda \in C^{2,\alpha}(\bar{\Omega})$ . The mapping  $\lambda \mapsto u_\lambda$  is real analytic in  $(0, \lambda_0)$  with values in  $C^{2,\alpha}(\bar{\Omega})$ . Moreover, it is decreasing and satisfies:*

$$\lim_{\lambda \rightarrow 0^+} \lambda^{\frac{1}{1-p}} u_\lambda(x) = \left( \frac{1}{|\partial\Omega|} \int_{\Omega} a \right)^{\frac{1}{1-p}}$$

where the limit is taken in  $C^{2,\alpha}(\bar{\Omega})$ .

- iii) [ $L^\infty$  estimate] *There exist constants  $\lambda_1 > 0$ ,  $C > 0$  such that every nonnegative solution  $u$  corresponding to  $\lambda \geq \lambda_1$  satisfies:*

$$0 \leq u(x) \leq C\lambda^{-\frac{2}{1-p}}.$$

- iv) [Dead core formation] *Every nonnegative solution  $u_\lambda \neq 0$  corresponding to  $\lambda \geq \lambda_2$ , for a certain  $\lambda_2 > 0$ , develops a dead core  $\mathcal{O}_\lambda = \{u_\lambda(x) = 0\}$  such that  $\mathcal{O}_\lambda \rightarrow \Omega$  as  $\lambda \rightarrow \infty$ . More precisely:*

$$\{x : \text{dist}(x, \partial\Omega) \geq d(\lambda)\} \subset \mathcal{O}_\lambda,$$

where  $d(\lambda) \rightarrow 0^+$  as  $\lambda \rightarrow \infty$ . Furthermore,  $d(\lambda)$  can be chosen as  $d(\lambda) = \frac{K}{\lambda}$ , for a certain constant  $K > 0$ , provided that  $a(x) > 0$  on  $\partial\Omega$ .

An important feature of the degenerate regime is that it exhibits multiple solutions when  $\lambda$  is sufficiently large. This is shown in the next result.

THEOREM 4.2. *Let  $\Omega \subset \mathbb{R}^N$  be a  $C^{2,\alpha}$  domain whose boundary  $\partial\Omega$  splits in  $k$  connected components, while  $a(x) \in C^\alpha(\bar{\Omega})$  is positive in  $\Omega$ . Then problem (1.1) admits at least  $2^k - 1$  nonnegative nontrivial solutions when  $\lambda$  is large enough.*

In view of this result, a question naturally arises: is the non connectedness of  $\partial\Omega$  the responsible for the multiplicity of solutions? The answer – in the negative – can be found in the next result, where  $\Omega$  is a ball, hence  $\partial\Omega$  is connected.

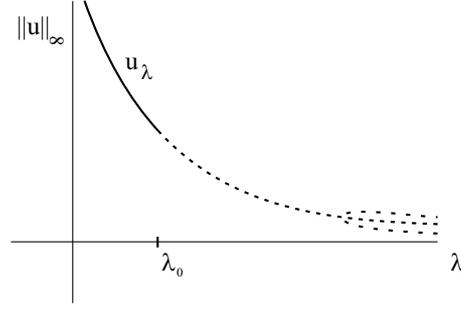


FIG. 4.1. Bifurcation diagram for  $a(x) > 0$ : the continuous line means uniqueness.

**THEOREM 4.3.** Consider problem (1.1) in a ball  $B$  of  $\mathbb{R}^N$ , with the coefficient  $a(x)$  radial and positive. Then problem (1.1) admits for every  $\lambda > 0$  a radial nonnegative solution  $u \neq 0$ . Such solution is unique for  $0 < \lambda < \lambda_0$ . Moreover:

- i) There exists a unique radial nonnegative solution  $u_\lambda \neq 0$  for large  $\lambda$  that satisfies:

$$\text{dist}(\mathcal{O}_\lambda, \partial B) \sim \beta \lambda^{-1}, \quad u_\lambda(1) \sim A \beta^\beta \lambda^{-\beta},$$

as  $\lambda \rightarrow +\infty$  where  $\beta = 2/(1-p)$ ,  $A = [\beta(\beta-1)]^{-1/(1-p)}$  and  $\mathcal{O}_\lambda = \{x \in B : u_\lambda = 0\}$ .

- ii) There exists  $\lambda_3 > 0$  such that problem (1.1) admits a solution  $u \neq 0$ , nonnegative and nonradial for every  $\lambda \geq \lambda_3$ .

**REMARK 5.** Suppose that  $a(x)$  satisfies H) with a nonempty domain  $\Omega_0$  so that  $\sigma_1 = \infty$ . Since this is equivalent to  $\overline{\Omega}_0 \subset \Omega$  ( $\Gamma_1 = \emptyset$ , see Section 2) then H)<sub>s</sub> is satisfied and it is possible to deduce for problem (1.1) the same conclusions obtained in Theorem 4.1. Namely:

- i) For  $\lambda > 0$ , problem (1.1) admits at least a nonnegative nontrivial solution  $u \in C^{2,\alpha_1}(\overline{\Omega})$ , and no solutions exist if  $\lambda \leq 0$ .
- ii) There exists a unique positive solution  $u \in C^{2,\alpha}(\overline{\Omega})$  for  $0 < \lambda < \lambda_0$  which bifurcates from infinity in  $\lambda = 0$ , with  $u_\lambda(x) \sim \left(\frac{1}{|\partial\Omega|} \int_\Omega a\right)^{\frac{1}{1-p}} \lambda^{-\frac{1}{1-p}}$  as  $\lambda \rightarrow 0+$ .
- iii) For large  $\lambda$ , nonnegative solutions  $u$  verify the estimate  $0 \leq u(x) \leq C \lambda^{-\frac{2}{1-p}}$ , where the constant  $C$  does not depend on  $u$ .
- iv) Also for large  $\lambda$ , all nonnegative solutions  $u$  develop a dead core  $\mathcal{O}_\lambda$  which satisfies  $\{x : \text{dist}(x, \partial\Omega) \geq d(\lambda)\} \subset \mathcal{O}_\lambda = \{u_\lambda(x) = 0\}$ ,  $d(\lambda) \rightarrow 0$  as  $\lambda \rightarrow \infty$ .

However, the situation is completely different to the regular regime  $p > 1$  when  $\sigma_1 < \infty$  ( $\Gamma_1 \neq \emptyset$ ). In strong contrast with the regular regime  $p > 1$ , the eigenvalue  $\sigma_1^+$  plays an important rôle in the degenerate case  $0 < p < 1$ . The next statement gives precise information on problem (1.1) when  $\sigma_1 < \infty$ .

**THEOREM 4.4.** Suppose that  $a(x)$  satisfies H) with  $\sigma_1 < \infty$  and assume either of the conditions H)<sub>s</sub> or H)<sub>m</sub>. Then there exists at least a nonnegative nontrivial solution  $u \in C^{2,\alpha_1}(\overline{\Omega})$ ,  $\alpha_1 = \min\{p, \alpha\}$ , with the same properties as the corresponding nonnegative solutions described in Theorem 4.1 whenever  $0 < \lambda < \sigma_1$ . Moreover:

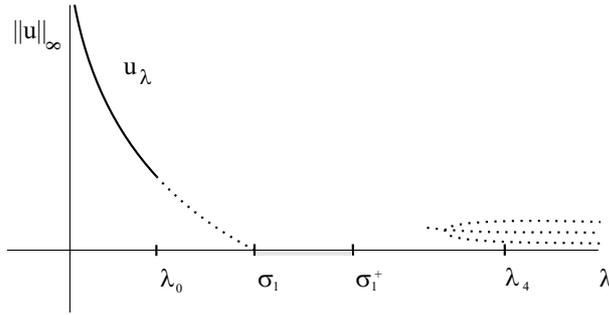


FIG. 4.2. Bifurcation when  $\sigma_1 < \infty$ : the continuous line stands for uniqueness.

- i) All nonnegative solutions  $u$  corresponding to  $\lambda \geq \sigma_1$  satisfy  $u \equiv 0$  in  $\Omega_0$ .
- ii) If  $\sigma_1^+ = \infty$ , there do not exist nonnegative nontrivial solutions for  $\lambda \geq \sigma_1$ .
- iii) If  $\sigma_1^+ < \infty$ , nonnegative nontrivial solutions can only occur in the range  $\lambda > \sigma_1^+$ . In particular, such solutions cannot exist for  $\lambda$  verifying:

$$\sigma_1 \leq \lambda \leq \sigma_1^+,$$

assuming  $\sigma_1 \leq \sigma_1^+$  (see Figure 4.2).

- iv) Assume that condition  $H)_s$  holds. Then, for  $\sigma_1^+ < \infty$  certain  $\lambda_1 > \sigma_1^+$  exists such that problem (1.1) admits at least a nonnegative nontrivial solution  $u$  for every  $\lambda \geq \lambda_1$ . Such solutions satisfy the estimate:

$$0 \leq u(x) \leq C \lambda^{-\frac{2}{1-p}},$$

and develop a dead core which verifies  $\mathcal{O}_\lambda \rightarrow \Omega$  as  $\lambda \rightarrow \infty$  in the form described in Remark 5-iv).

To conclude with the description of the qualitative properties of nonnegative solutions to problem (1.1) in the degenerate case, we give sufficient conditions providing the existence of a bifurcation from  $u = 0$  in  $\lambda = \sigma_1$ .

**THEOREM 4.5.** *Assume that  $a(x)$  satisfies  $H)$  and either of the hypotheses  $H)_s$  or  $H)_m$ . If  $\sigma_1 < \infty$  and one of the following conditions holds: either  $\sigma_1 \leq \sigma_1^+$  or  $\sigma_1^+ < \sigma_1$  but  $u = 0$  is the only nonnegative solution for  $\lambda = \sigma_1$ , then:*

$$u_\lambda \rightarrow 0 \quad \text{as } \lambda \rightarrow \sigma_1^-,$$

in  $C^{2,\alpha_1}(\bar{\Omega})$ . On the other hand, every possible solution develops a dead core  $\mathcal{O}_\lambda \subset \Omega^+$  such that  $\mathcal{O}_\lambda \rightarrow \Omega^+$  as  $\lambda \rightarrow \sigma_1^-$ .

**REMARK 6.** Last assertion in Theorem 4.5 implies that solutions  $u_\lambda$  of (1.1) converging to zero as  $\lambda \rightarrow \sigma_1^-$  develop their dead cores  $\mathcal{O}_\lambda$  into  $\Omega^+$ , being strictly positive in  $\Omega_0$ . This should be contrasted with the behavior of nonnegative solutions to the problem (if any) in the range  $\lambda \geq \sigma_1$ . In fact, the latter must be identically zero in  $\Omega_0$  (Theorem 4.4, i)).

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